

### FOG INERTIAL NAVIGATION SYSTEM

#### **FEATURES**

- Multimode Kalman filter
- Accepts External Aiding Data
- Tactical class IMU, <0.1 °/ hr gyro</li>
- Centimeter level position accuracy with RTK
- Multi-Constellation L1/L2/L5 GNSS with IRNSS
- Superior tracking robustness under heavy mechanical shocks or vibrations
- Isolated Interfaces and Power Supply
- MIL qualified to MIL-STD-810G, JSS55555, MIL-STD-461E and MIL-STD 704D



#### **APPLICATIONS**

- Unmanned Aerial Vehicle
- Marine Navigation
- Armoured Vehicle Navigation
- Antenna Stabilization and Control
- Autonomous Vehicle Navigation
- Antenna Orientation and Stabilization
- Mapping and Surveying
- Land Navigation

#### **DESCRIPTION**

Aldebaran ALD-NS3500S is a rugged GNSS aided high performance Fiber Optic Gyro (FOG) based Inertial Navigation System. The device incorporates high end tactical class three axis accelerometers, three axis fiber-optic gyroscopes and an integrated multi-constellation GNSS receiver. The sensors are characterized and calibrated in Aeron's state of art facility. Aeron's proprietary parameter estimation engine delivers fast alignment and tactical class navigation performance in a matter of minutes.

The ALD-NS3500S model has a multi-frequency (L1/L2/L5), multi-constellation GNSS receiver with multi tracked channels and best in class signal sensitivity. The ALD-NS3500S model has a multi-frequency (L1/L2/L5), multi constellation GNSS receiver including IRNSS and best in class signal sensitivity.

The Aldebaran series INS offers superior pure-inertial performance in short term GNSS outages. External air data/velocity and position aiding can also be provided to the system. ALD-NS3500S is suitable for positioning and pointing in airborne, land & naval applications.

MADE IN INDIA

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## **TECHNICAL SPECIFICATIONS**

Parameter Value  Acceleration  Range (g)  Bias Instability (µg)  Bias Repeatability (mg)  Raw Bandwidth (kHz)  Angular Rate  Range (°/s)  Bias Instability (°/hr)	#10  15  1.2  >1  ±450  0.1  >1
Range (g) Bias Instability (µg) Bias Repeatability (mg) Raw Bandwidth (kHz)  Angular Rate Range (°/s)	±10 15 1.2 >1 ±450 0.1
Range (g) Bias Instability (µg) Bias Repeatability (mg) Raw Bandwidth (kHz)  Angular Rate Range (°/s)	15 1.2 >1 ±450 0.1
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Bias Repeatability (mg) Raw Bandwidth (kHz)  Angular Rate Range (°/s)	1.2 >1 ±450 0.1
Raw Bandwidth (kHz)  Angular Rate  Range (°/s)	>1 ±450 0.1
Raw Bandwidth (kHz)  Angular Rate  Range (°/s)	±450 0.1
Range (°/s)	0.1
	0.1
Bias Instability (°/hr)	**-
	>1
Raw Bandwidth (kHz)	
ARW (°/sqrt(hr))	<0.012
Position/ Velocity Accuracy	0.0 11.5-15
420	<0.8 cm with RTK <sup>5</sup> 1.5 m with GNSS
Horizontal Position <sup>1,2,3</sup>	1 m with SBAS
	0.3% of DT with External Odometer <sup>4</sup>
	<2 cm with RTK <sup>5</sup>
Vertical Position <sup>1,2,3</sup>	2.5 m (1o) with GNSS
Vertical i Osition	1.5 m (1σ) with SBAS
	2 m (1σ) relative with Barometer
Velocity (m/s)	0.05 RMS with GNSS <sup>8</sup>
Attitude	
Roll Range (degree)	±180
Pitch Range (degree)	±90
Roll, Pitch Accuracy (degree)	$\pm 0.05$ (2 $\sigma$ ) (Static/ low dynamics) $\pm 0.1$ (1 $\sigma$ ) Dynamic
Roll, Pitch Resolution (degree)	0.01
Heading	
Heading Range (degree)	±180
Heading Accuracy <sup>1,2,6,7</sup>	0.5° RMS with magnetometer 0.3° RMS with GNSS in dynamic conditions 0.3° RMS with GNSS in dynamic conditions 0.5° RMS with magnetometer 0.5° RMS with magnet
Resolution (degree)	0.01
GPS / GNSS	
	Iulti channel, L1/ L2/ L5 Code / Carrier phase PS, GLONASS, QZSS, BEIDOU and IRNSS/NavIC
Diff. Correction Type <sup>4</sup>	RTCMv2, RTCMv3, CMRv2 (for RTK mode)
TTFF <sup>6</sup> Cold Start (seconds)	45
Reacquisition Time (seconds)	1
Connector	TNC Socket
Barometer	
Range (hPa)	300-1100
Accuracy (hPa)	±1
Type MGP  Diff. Correction Type <sup>4</sup> TTFF <sup>6</sup> Cold Start (seconds)  Reacquisition Time (seconds)	Iulti channel, L1/ L2/ L5 Code / Carrier phase PS, GLONASS, QZSS, BEIDOU and IRNSS/NavIC RTCMv2, RTCMv3, CMRv2 (for RTK mode) 45

- 1 Open sky conditions
- 2 RMS levels
- 3 Baseline <40 km
- 4 RTK mode of operation requires differential corrections from RTK base station
- 5 Time to First Fix
- ${\bf 6}$  Accuracy after magnetic calibration and setting correct declination / offset angle
- 7 After magnetic calibration for Hard Iron and Soft Iron disturbances, and in static magnetic field
- 8 50% at 30 m/s for dynamic operation

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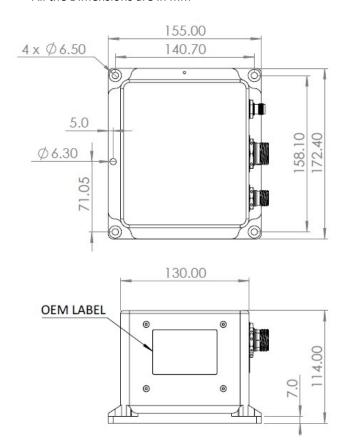
	Parameter Value	
Parameter Value	Aldebaran	
	NS3500S	
Electrical		
Input Voltage (V DC)	12 to 32	
Power Consumption (W)	<10	
Update Rate (Hz)	100 (Navigation) 200 (Raw measurement)	
Interface	RS232(CH1), RS232(CH2) <sup>5</sup> , RS422 x 2, 1PPS	
Data Format	NMEA / Binary	
External Inputs	External GNSS feed External Magnetometer feed External Airspeed feed External Position and Speed input	
Physical		
Dimensions (mm)	172.4 (L) x 155 (W) x 114 (H)	
Weight (kg)	2.5 ±0.05	
Environment		
Operating Temperature (°C)	-40 to +71	
Storage Temperature (°C)	-55 to +85	
IP Protection	IP65	
Hardware Design Compliant		
Power Supply	MIL-STD-704D*	
EMI/EMC	MIL-STD-461E*	
Environmental Tests	MIL-STD-810G*	

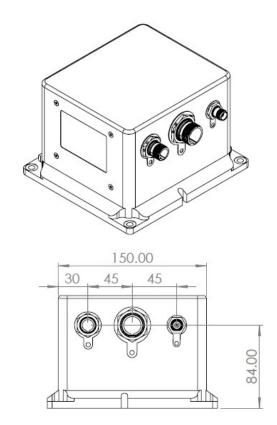
<sup>\*-</sup>MIL-STD qualified



### **MECHANIAL DIMENSIONS**

All the Dimensions are in mm





## **ORDERING INFORMATION**

ALD-NS3500S (Product Code: 25022)

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